

Yuhang Lu

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EDUCATION

- **Beijing University of Posts and Telecommunications** Beijing, China
Bachelor of Engineering in Internet of Things Engineering; GPA: 87.9/100 Sept. 2018 – Jun. 2022
Main Courses: Linear Algebra(90), Discrete Mathematics(97), Probability Theory and Stochastic Processes(87), Data Structures(94), Operating System(83), Database(86), Network and Protocols(97), Cloud Computing(92).
- **Queen Mary University of London** London, UK
Bachelor of Engineering in Internet of Things Engineering; First Class Degree Sept. 2018 – Jun. 2022

WORK EXPERIENCE

- **ShanghaiTech University** Shanghai, China
Research Assistant (Supervisor: Yuexin Ma) Aug. 2022 - Present
 - Led and contributed to cutting-edge research in 3D visual perception, focusing on developing label-efficient and memory-optimized perception systems for autonomous driving.
 - Conceptualized and proposed novel solutions to enhance model performance, improving accuracy and efficiency in specific tasks.
 - Spearheaded the implementation of key project code and played a lead role in drafting, revising, and submitting research papers for publication.

RESEARCH INTERESTS

My research focuses on advancing AI's ability to understand the 3D world with human-like perception.

Currently, I am working on:

- Developing resource-efficient perception algorithms with minimal annotations and low memory overhead.
- Leveraging VLMs' reasoning abilities to improve model performance and generalization.
- Incorporating rule-based constraints into autonomous driving planning models to ensure safe and comfortable decision-making.

PUBLICATIONS

- **Yuhang Lu, Yichen Yao, Jiadong Tu, Jiangnan Shao, Yuexin Ma, Xinge Zhu. Can LVLMs Obtain a Driver's License? A Benchmark Towards Reliable AGI for Autonomous Driving.** Arxiv preprint(Under Review)
- **Yuhang Lu, Xinge Zhu, Tai Wang, Yuexin Ma. OctreeOcc: Efficient and Multi-Granularity Occupancy Prediction Using Octree Queries.** Conference on Neural Information Processing Systems (NeurIPS), 2024
- **Yuhang Lu, Qi Jiang, et al. See More and Know More: Zero-shot Point Cloud Segmentation via Multi-modal Visual Data.** Proceedings of the IEEE/CVF International Conference on Computer Vision (ICCV), 2023.

RESEARCH EXPERIENCE

- **Research on multimodal zero-shot point clouds segmentation**
ICCV 2023 Poster(Supervisor: Yuexin Ma) Jun. 2022 - Feb. 2023
 - Proposed a novel multimodal zero-shot approach for point cloud semantic segmentation.
 - Designed an effective feature-fusion method with semantic-visual feature enhancement, improving alignment between visual and semantic features for better recognition of unseen classes.
 - Achieved state-of-the-art performance on SemanticKITTI and nuScenes datasets.

- **Research on efficient camera-based occupancy prediction**

NeurIPS 2024 Poster(Supervisor: Yuexin Ma and Tai Wang)

Mar. 2023 - Oct. 2023

- Introduce a 3D occupancy prediction framework using multi-granularity octree query, which sparsifying space, reducing necessary voxels and preserving vital spatial information.
- Develop a semantic-guided octree initialization module and an iterative structure rectification module to provide the network with optimal initialization and dynamic octree adjustments for enhanced representation.
- Achieve state-of-the-art performance while reducing around 20% computational overhead

- **Research on driving knowledge data and its boost for downstream VLMs**

Under Review(Supervisor: Yuexin Ma and Xinge Zhu)

Mar. 2024 - Sep. 2024

- Introduce IDKB, the first large-scale vision-language dataset explicitly containing both driving theory and practical knowledge.
- Evaluated 15 leading Large Vision-Language Models (LVLMs) on the IDKB dataset, providing a comprehensive analysis of their driving capabilities.
- Led a team of three co-authors to successfully complete the project, overseeing all phases of development and research.

SKILLS SUMMARY

- **Languages:** Chinese (native), English (IELTS 7)
- **Programming Tools:** Python, Java, Pytorch, GIT
- **Hobbies:** Basketball, billiards